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LASER SENSORS

SENSORS MICRO PHOTOELECTRIC SENSORS AREA SENSORS SAFETY COMPONENTS PRESSURE SENSORS INDUCTIVE PROXIMITY SENSORS PARTICULAR USE SENSORS

SENSOR OPTIONS WIRE-SAVING SYSTEMS

STATIC CONTROL DEVICES

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Displacement

Lase

HL-C2

HL-C1 LM10

**GP-X** 

GP-A Collimated Beam Sensors

HL-T1

LA-300

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LA

SENSORS

PHOTOELECTRIC

# High Speed · High Accuracy Eddy Current Type Digital Displacement Sensor



## High-speed sampling and high resolution. The new choice for even more variegated data collection and processing.

## They perform with a ±0.3 % F.S. linearity for stainless steel and iron

Because they perform with a  $\pm 0.3 \%$  F.S. linearity, they can be used for sensing stainless steel and iron enabling precise measurements not affected by the work's material. Specifications corresponding to each material (stainless steel, iron, aluminum) has already been inputted in the controller enabling the easy selection of the setting that is most suitable for the particular material used.

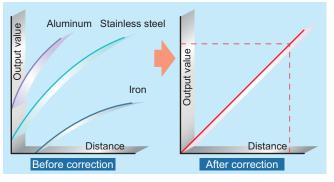
## We've realized a 25 µs (40,000 times/sec.) ultra high sampling speed

With a 25 µs ultra high sampling speed, the **GP-X** series won't miss even high speed work displacements.

## These devices boast a 0.07 % F.S./°C temperature characteristics

By combining the sensor head with the controller, we've realized 0.07 % F.S./°C. They are highly resistant to ambient temperature changes enabling stable micro-displacement measurements.

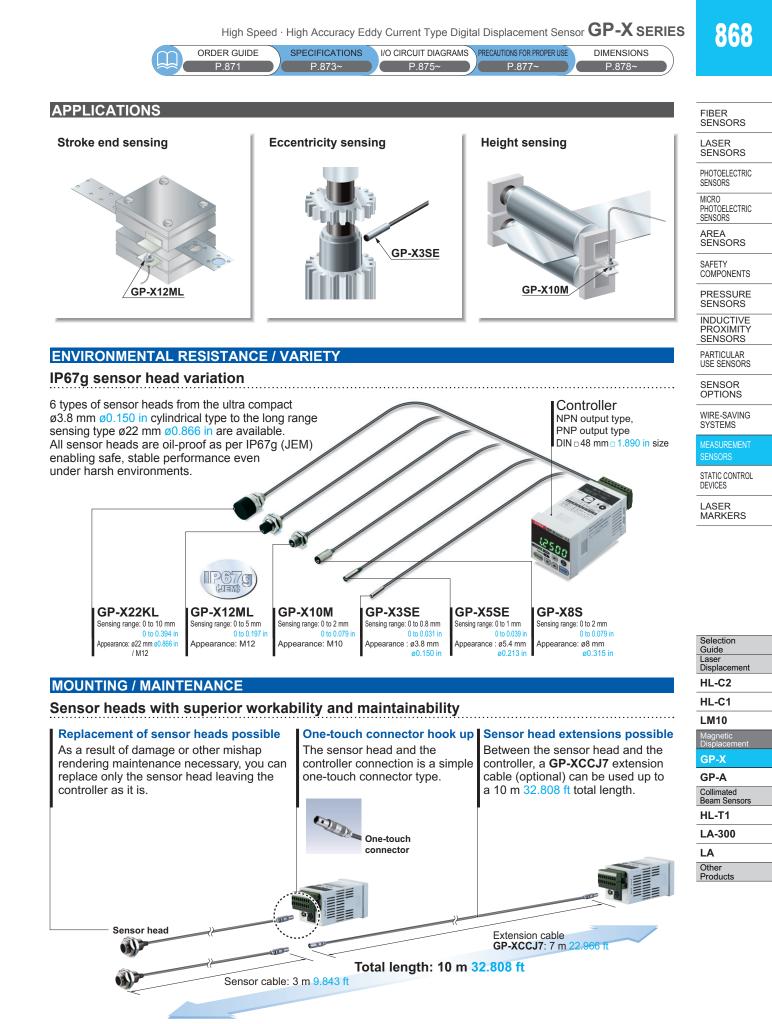
## Optimal correction of the output feature



## They possess a 0.02 % F.S. resolution for highly accurate measurement

With high resolution, 0.02 % F.S. (Note), they can perform high-accuracy measurements of micro-displacements. In particular, the sensor head **GP-X3SE** for 0.8 mm 0.049 in sensing can differentiate ultra micro displacement of 0.32 µm 0.013 mil (Average number of samples: 64). Note: **GP-XC3SE** and **GP-XC5SE** Resolution: 0.04 % F.S.

SUNX



SUNX

LASER SENSORS

MICRO PHOTOELECTRIC

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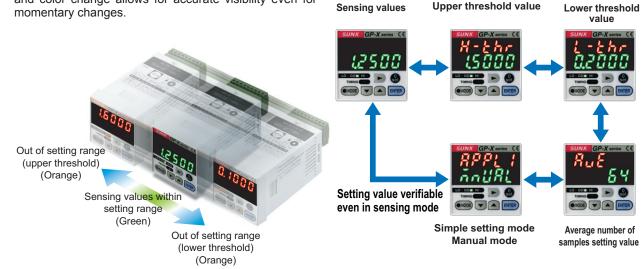
## FUNCTIONS

## The 5-digit, dual, 2-color digital display offers great visibility

If the measurement results fall within the setting range (GO), they will appear on the lower digital display in green. If they are out of range (HI, LO), they will be displayed in the upper digital display in orange. The display position and color change allows for accurate visibility even for momentary changes.

Digital input display enabling easy setting

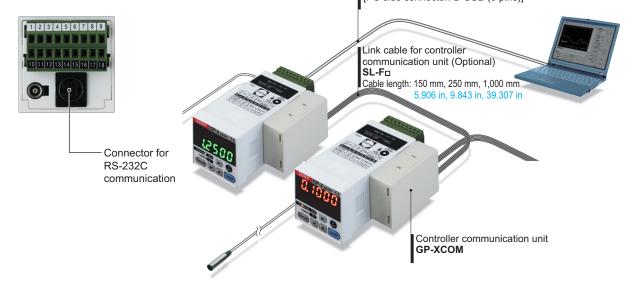
Its dual digital display enables numerical setting while verifying setting items for each mode. Even when sensing, it enables the verification of the main settings.



## The RS-232C communication connector is standard equipment

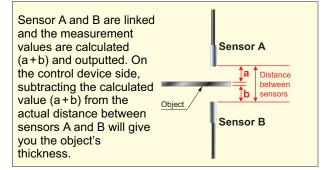
It is capable of various controls such as saving measurement data to PC and the controller's inputted settings and loading stored memory.

#### Exclusive RS-232C cable (Accessory for the intelligent monitor **GP-XAiM**) Cable length: 3 m 9.843 ft [PC side connector: D-SUB (9 pins)]



## Enables sensors data comparisons and calculations

3-value judgment output for calculating measurement data conformity and calculation results between 2 interconnected controllers is rendered possible. The calculation function equipment renders digital panel controllers unnecessary.



Displacement HL-C2 HL-C1 LM10 Magnetic Displacement GP-X GP-A Collimated Beam Sensors HL-T1 LA-300 LA Other Products

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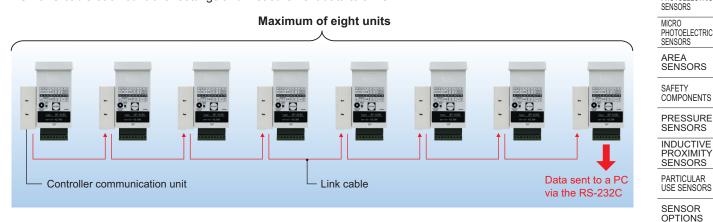
SYSTEMS

LASER SENSORS

## OPTIONS

## Datalink between sensors possible

The controller communication unit **GP-XCOM** (optional) can be linked to up to 8 controllers and load via just one RS-232C cable each controller settings and measurement data to a PC.



## An intelligent monitor (GP-XAiM) optimal for collecting and analyzing measurement data is also available

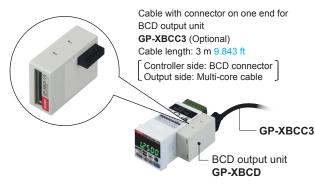
An intelligent monitor capable of the settings for each measurement conditions and waveform display monitoring. It can perform waveform monitoring, which could until now only be done by the oscilloscope, as well as the simple loading and saving onto a PC of settings for each condition and function. (Exclusive RC-232C cable is attached.)



## BCD output unit GP-XBCD (Optional)

## 20 kHz high-speed data output

The measurement data can be processed quickly in the PLC. (Sampling rate: 20 kHz)



## 4 types of measurement modes available

Measurement modes compatible to the most widely used applications are available. Because of this, inputting setting values can be done with ease. Please select the most appropriate mode to suit your specific application. Mutual interference prevention function

The sensor head can be made interference prevention by linking up to 8 controllers via an interference prevention output cable and shifting the oscillation timing. This enables precise measurements to be obtained even in cases where many sensor heads are crowded in the same area.

## Removable type terminal block

It is equipped with a removable type European terminal block very convenient during assembly, when dividing the equipment into segments or when performing maintenance. It also features an reverse insertion prevention construction.

4 types of selectable memory functions

The setting data can be processed in 4 types of memory

of the workpiece, the sensing of multiple products or

when measuring. This function enables either the changing

European terminal block

Beam Sensors
HL-T1
LA-300
LA
Other

sensing after product changeover to be done smoothly. <Maunally set mode>



<Stroke end sensing mode>



<Rotation / eccentricity / vibration sensing mode>



<Height sensing mode>



Selection Guide
Laser Displacement
HL-C2



## ORDER GUIDE

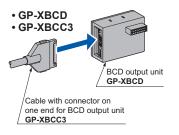
LASER SENSORS	-	Appear	ance (mm in)		Set Model No.	
PHOTO- ELECTRIC	Туре	Sensor heads	Controller	Sensing range	(Sensor head model No.)	Comparative output
MICRO PHOTO- ELECTRIC SENSORS		ø3.8 ø0.150		□ 0 to 0.8 mm	GP-XC3SE (GP-X3SE)	NPN open-collector transistor
AREA SENSORS	or head	17*0.669		0 to 0.031 in	GP-XC3SE-P (GP-X3SE)	PNP open-collector transistor
SAFETY COMPONENTS	pe sens	ø5.4 ø0.213		□ 0 to 1 mm	GP-XC5SE (GP-X5SE)	NPN open-collector transistor
PRESSURE SENSORS	eaded ty	vo.213 v.669 v.213 v.669 v.213 v.669 v.213 v.669 v.213 v.669 v.213 v.669 v.213 v.669 v.213 v.669 v.213 v.669 v.213 v.669 v.213 v.669 v.213 v.217 v.669 v.213 v.217		0 to 0.039 in         GP-XC5SE-P (GP-X5SE)           0 to 2 mm 0 to 0.079 in         GP-XC8S (GP-X8S)           0 to 2 mm 0 to 0.079 in         GP-XC8S-P (GP-X8S)           0 to 2 mm 0 to 0.079 in         GP-XC10M (GP-X10M)           0 to 2 mm 0 to 0.079 in         GP-XC10M (GP-X10M)		PNP open-collector transistor
INDUCTIVE PROXIMITY SENSORS	Non-thr		83			NPN open-collector transistor
PARTICULAR USE SENSORS		ø8 ø0.315 0.669				PNP open-collector transistor
SENSOR OPTIONS WIRE-						NPN open-collector transistor
SAVING SYSTEMS MEASURE- MENT	head	M10 17 0.669	48		••••••••••	PNP open-collector transistor
SENSORS STATIC CONTROL	e sensor head	0 to 5 mm 0 to 5 mm 0 to 0.197 in		GP-XC12ML (GP-X12ML)	NPN open-collector transistor	
LASER MARKERS	d ty		0 to 0.197 in	GP-XC12ML-P (GP-X12ML)	PNP open-collector transistor	
		M12		0 to 10 mm	GP-XC22KL (GP-X22KL)	NPN open-collector transistor
		ø22 ø0.866 1.378		0 to 0.394 in	GP-XC22KL-P (GP-X22KL)	PNP open-collector transistor

Selection Guide
Laser Displacement
HL-C2
HL-C1
LM10
Magnetic Displacement
GP-X
GP-A
Collimated Beam Sensors
HL-T1
LA-300
LA
Other Products

## **OPTIONS**

Designation	Model No.	Description			
BCD output unit	GP-XBCD	This unit outputs meas speed. • Sampling frequency	urement values in BCD data format at a high		
Cable with connector on one end for BCD output unit	GP-XBCC3	Length: 3 m 9.843 ft Cable for BCD data output unit • 26-core cable with connector on one end			
Controller communication unit	GP-XCOM	Up to 8 controllers can be linked			
Link cable for	SL-F150	Length: 150 mm 5.906 in			
controller	SL-F250	Length: 250 mm 9.843 in	This cable links the controller communication units. Select as per the cable length.		
communication unit	SL-F1000	Length: 1,000 mm 39.370 in			
Intelligent monitor	GP-XAiM	Monitoring settings for each measurement condition and measurement waveforms is enabled by way of a PC. • One exclusive RS-232C cable (3 m 9.843 ft length) is attached.			
Extension cable for sensor head	GP-XCCJ7	Length: 7 m 22.966 ft This cable with connector is for extension between the sensor head and controller.			
	MS-SS3	Mounting bracket for G	P-X3SE		
Sensor head mounting bracket	MS-SS5	Mounting bracket for G	P-X5SE		
	MS-SS8	Mounting bracket for GP-X8S			

#### **BCD** output unit Cable with connector on one end for BCD output unit



## Sensor head mounting bracket

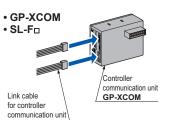
#### • MS-SSD



The sensor head can be easily fixed.

#### **Controller communication unit** Link cable for controller communication unit

SL-Fo



Intelligent monitor • GP-XAiM

## Extension cable for sensor head

• GP-XCCJ7





SENSOR OPTIONS

PRESSURE SENSORS

## SPECIFICATIONS

## Controllers

LASER SENSORS	Con	trollers					
PHOTO- ELECTRIC	$\bigvee$	Туре	NPN output	PNP output			
SENSORS	Item	Set model No.	GP-XC□	GP-XC□-P			
MICRO PHOTO- ELECTRIC SENSORS	Supply voltage		24 V DC ± 10 % Ripple P-P 10 % or less				
AREA	Current consumption		150 mA or less				
SENSORS	Reso	olution (Note 2)	GP-XC3SE / GP-XC5SE: 0.04 % F.S. (64 times GP-XC8S / GP-XC10M / GP-XC12ML / GP-XC2	average processing) 2KL: 0.02 % F.S. (64 times average processing)			
COMPONENTS	Sam	pling frequency	40 kHz	(25 µs)			
PRESSURE SENSORS	Line	arity (Note 2)	Within ±0	.3 % F.S.			
INDUCTIVE	Temp	erature characteristics (Note 3)	0.07 % F.S	./°C or less			
PROXIMITY SENSORS	Anal	og voltage outputs	Output voltage: -5 to +5 V (Note 4)	, Output impedance: 100 Ω approx.			
PARTICULAR USE		Response time	75 μs (maxir	num speed)			
SENSORS SENSOR OPTIONS WIRE- SAVING SYSTEMS		parative outputs GO, LO)	<ul> <li>NPN open-collector transistor</li> <li>Maximum sink current: 100 mA</li> <li>Applied voltage: 30 V DC or less (between comparative output and 0 V)</li> <li>Residual voltage: 1.6 V or less (at 100 mA sink current) 0.4 V or less (at 16 mA sink current)</li> </ul>	<ul> <li>PNP open-collector transistor</li> <li>Maximum source current: 100 mA</li> <li>Applied voltage: 30 V DC or less (between comparative output and +V)</li> <li>Residual voltage: 1.6 V or less (at 100 mA source current) 0.4 V or less (at 16 mA source current)</li> </ul>			
MEASURE- MENT		Utilization category	DC-12 o	r DC-13			
SENSORS		Output number	HI / GO / LO 3	3 value output			
STATIC CONTROL DEVICES		Output operation	HI ∶ ON when measured value > the upper limit value GO: ON when upper limit value ≥ measured value ≥ lower limit value LO ∶ ON when lower limit value > measured value				
MARKERS		Short-circuit protection	Incorporated				
	External input		Photo-coupler input       • Input current: 9 mA or less         • Operating voltage: ON voltage 17 V or more (between +24 V and input)       • Input current: 9 mA or less         • OFF voltage 4 V or less (between +24 V and input)       • OFF voltage 17 V or more (between 0 V and input)         • Input impedance: 5 kΩ approx.       • Input impedance: 5 kΩ approx.				
	Seria	al I/O	RS-2	232C			
Selection	Zero	-set setting method	Push button setting / External input setting				
Guide		MODE	Orange LED (lights up	when in mode status)			
Displacement	ors	ні	Orange LED (lights up when the	e upper limit value is exceeded)			
HL-C2	Indicators	GO	Green LED (lights up when within the upper and lower limit value)				
HL-C1	Ē	LO	Orange LED (lights up when less than the lower limit value)				
LM10 Magnetic		TIMING	Green LED (lights up as per the	external or internal trigger timing)			
Displacement	Uppe	er level digital display part	5 digit orange LED (display of numerical	values out of upper and lower limit value)			
GP-X GP-A		er level digital display part	5 digit green LED (display of numerical val	ues within the upper and lower limit value)			
Collimated	Environmental resistance	Pollution degree	3 (Industrial e	environment)			
Beam Sensors	Ambient temperature		0 to +50 °C +32 to +122 °F (No dew condensation), Storage: 0 to +50 °C +32 to +122 °F				
HL-T1 LA-300	ital r	Ambient humidity	35 to 85 % RH, Stor	age: 35 to 85 % RH			
	men	EMC	EN 61000-6-2,	EN 61000-6-4			
LA Other	viron	Vibration resistance	10 to 55 Hz frequency, 0.75 mm 0.030 in amplit	ude in X, Y and Z directions for two hours each			
Products	En	Shock resistance	100 m/s <sup>2</sup> acceleration (10 G approx.) in	X, Y and Z directions for five times each			
	Mate	erial	Enclosure: P	olycarbonate			
	Weight		ight Net weight: 120 g approx.				
	Weig	jht	Net weight: 1	20 g approx.			

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +20 °C +68 °F.

2) This value was obtained at a constant +25 °C +77 °F

3) This value represents 20 to 60 % of the maximum sensing distance when combining the sensor head and controller.
4) Adjusted to a 0 to +5 V factory setting.

## SPECIFICATIONS

#### **Sensor heads**

-		Type Non-threaded type			Threaded type			
			For 0.8 mm 0.031 in sensing	For 1 mm 0.039 in sensing	For 2 mm 0.079 in sensing	For 2 mm 0.079 in sensing	For 5 mm 0.197 in sensing	For 10 mm 0.394 in sensing
Iten	ı 🔪	Model No.	GP-X3SE	GP-X5SE	GP-X8S	GP-X10M	GP-X12ML	GP-X22KL
Sen	sing range (N	lote 2)	0 to 0.8 mm 0 to 0.031 in	0 to 1 mm 0 to 0.039 in	0 to 2 mm 0 to 0.079 in	0 to 2 mm 0 to 0.079 in	0 to 5 mm 0 to 0.197 in	0 to 10 mm 0 to 0.394 in
Star	idard sensing	g object	Stainless ste	el (SUS304) / Iron she	et [Cold rolled carbon	steel (SPCC)] 60 × 60	× t 1 mm 2.362 × 2.36	2 × t 0.039 in
Temp	perature charac	cteristics (Note 3)			0.07 % F.S	./°C or less		
	Pollution de	egree			3 (Industrial	environment)		
nce	Protection			IP67 (IEC),	IP67g (JEM) (Refer to	p.1010 for defails of	standards.)	
sista	Ambient ter	nperature		–10 to +55 °	C +14 to +131 °F, Sto	orage: –20 to +70 °C -	-4 to +158 °F	
alre	Ambient hu	midity	35 to 85 % RH, Storage: 35 to 85 % RH					
Protection Ambient temperature Ambient humidity Voltage withstandability Insulation resistance			250 V AC for one min. between all supply terminals connected together and enclosure					
			20 M $\Omega$ , or more, with 250 V DC megger between all supply terminals connected together and enclosure					
Vibration resistance 10 to 150 Hz frequency, 0.1			.75 mm 0.030 in ampl	itude in X, Y and Z dir	rections for two hours	each		
	Shock resis	stance		500 m/s <sup>2</sup> acceleration	tion (50 G approx.) in	X, Y and Z directions	for five times each	
al	Enclosure			Stainless ste	el (SUS303)		Brass (Nic	kel plated)
Material	Cable prote	ector				PP		
Σ	Sensing pa	rt	ABS	PAR	AE	3S	Р	A
Cable			High frequency coaxial cable with connector, 3 m 9.843 ft long (Note 4)					
Cab	le extension			Extension up	to total 10 m 32.808 f	t is possible with the c	optional cable.	
Net	Weight (Note	e 5)	40 g approx.	40 g approx.	40 g approx.	50 g approx.	45 g approx.	80 g approx.
Accessories			·		Nut: 2 pc	cs., Toothed lock wash	ner: 1 pc.	

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +20 °C +68 °F.

2) The sensing range is specified for the standard sensing object.

3) This value represents 20 to 60 % of the maximum sensing distance when combining the sensor head and the controller.

4) For the flexible cable type, please contact our office.

5) The given weight of the threaded type sensor head is the value including the weight of the nuts and the toothed lock washer.

## **BCD** output unit

Model No. Item	GP-XBCD
Current consumption	20 mA or less
Outputs (5 digits BCD, Polarity indication, VALID)	N-channel MOSFET open drain • Maximum sink current: 50 mA • Applied voltage: 30 V DC or less (between output and GND) • Residual voltage: 1 V or less (at 50 mA sink current)
Hold input	Non-voltage contact or NPN open-collector transistor input • Low: 0 to 1 V • High: Open
Material	Enclosure: ABS
Weight	Net weight: 30 g approx.
Accessory	Mounting bracket [Stainless steel (SUS304)]: 1 pc.

Note: Connects to the control device with GP-XBCC3 cable with connector on one end for BCD output unit (3 m 9.843 ft cable length, optional).

#### **Controller communication unit**

Model No.	GP-XCOM	- Guide Laser Displacement					
		HL-C2					
Current consumption	5 mA or less	HL-C1					
Material	Enclosure: ABS	LM10					
Weight	Net weight: 20 g approx.	Magnetic Displacement					
Accessory	Mounting bracket [Stainless steel (SUS304)]: 1 pc.	GP-X					
Note: Each <b>GP-XCOM</b> is connected using a link cable for controller communication units ( <b>SL-F</b> <sub>D</sub> , optional).							
When <b>GP-XCOM</b> is used, controllers cannot communicate if their software versions are not compatible (Ver. 1.06 or earlier version with Ver 2.00 or later version). Check the software version and use the correct combination.							



CRO OTO-ECTRIC NSORS

EA NSORS

ETY //PONENTS

ESSURE NSORS

DUCTIVE OXIMITY NSORS

RTICULAR SORS

NSOR TIONS

RE-VING 'STEMS

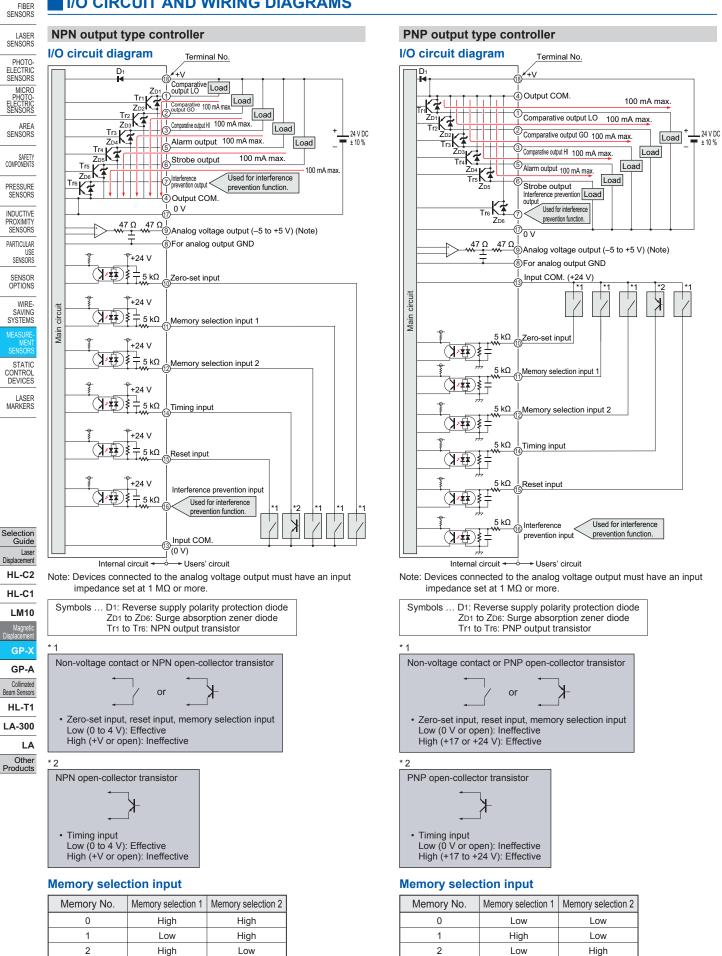
ATIC NTROL VICES

SER ARKERS

LA

Other Products

## I/O CIRCUIT AND WIRING DIAGRAMS



3

High

High

3

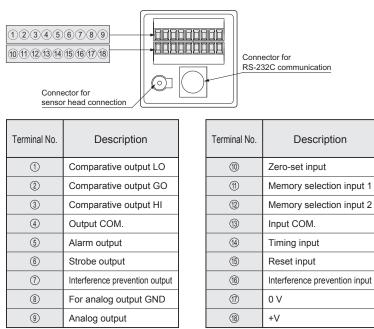
Low

Low

## I/O CIRCUIT AND WIRING DIAGRAMS

### Controller

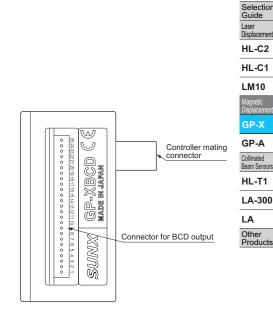
## **Terminal arrangement**



## **BCD** output unit

#### Connector pin position and cable color

Connector	Cable		Signal	Description			
pin No.	Sheath color ID mar		Signal	Description			
1	Orange	Red: 1	A0	1 ×			
2	Orange	Black: 1	B0	2 ×	Measurement value		
3	Gray	Red: 1	C0	4 ×	to the 10° digit		
4	Gray	Black: 1	D0	8 ×	-		
(5)	White	Red: 1	A1	1 ×			
6	White	Black: 1	B1	2 ×	Measurement value		
(7)	Yellow	Red: 1	C1	4 ×	to the 10 <sup>1</sup> digit		
8	Yellow	Black: 1	D1	8 ×			
9	Pink	Red: 1	A2	1 ×			
10	Pink	Black: 1	B2	2 ×	Measurement value to the 10 <sup>2</sup> digit	Measurement value BCD output	
(1)	Orange	Red: 2	C2	4 ×			
(12)	Orange	Black: 2	D2	8 ×	-		
(13)	Gray	Red: 2	A3	1 ×			
(14)	Gray	Black: 2	B3	2 ×	Measurement value		
(15)	White	Red: 2	C3	4 ×	to the 10 <sup>3</sup> digit		
(16)	White	Black: 2	D3	8 ×	-		
(17)	Yellow	Red: 2	A4	1 ×			
(18)	Yellow	Black: 2	B4	2 ×	Measurement value		
(19)	Pink	Red: 2	C4	4 ×	to the 10 <sup>₄</sup> digit		
20	Pink	Black: 2	D4	8 ×	-		
21)	Orange	Red: 3	POLE	Polari	ty signal output	High (OFF): +, Low (ON): -	
2	Orange	Black: 3	VALID	VALID output		Low (ON) when the data output is enabled	
23	Gray	Red: 3	HOLD	Hold input		This input is to maintain the externa data output. The data output is maintained during low (ON)	
24)	Gray	Black: 3	GND	Grour	ıd		
25	White	Red: 3	GND	Grour	ıd		
_	White	Black: 3		Not co	onnected	Not used	



Note: The shield wire is connected externally at 0 V.



FIBER SENSORS LASER SENSORS

PHOTO-ELECTRIC SENSORS MICRO PHOTO-ELECTRIC SENSORS

AREA SENSORS

SAFETY COMPONENTS

PRESSURE SENSORS

INDUCTIVE PROXIMITY SENSORS PARTICULAR

SENSOR OPTIONS

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Selection Guide Laser Displacement HL-C2

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Displacement

HL-C2

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**GP-X** GP-A Collimated Beam Sensors

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Lase

## **PRECAUTIONS FOR PROPER USE**

- Never use this product as a sensing device for personnel protection. In case of using sensing devices for personnel protection, use products which
  - meet laws and standards, such as OSHA, ANSI or IEC etc., for personnel protection applicable in each region or country.
- · The sensor head and the controller are adjusted in order to conform to the default specification linearity.
- · In the event of replacing sensor heads, input the sensor head's characteristic code and conduct 3-point correction (calibration).
- Should you use an extension cable, turn the sensor head cable length selection switch located on the back of the controller to "3 m + 7 m 9.843 ft + 22.966 ft". Then reintroduce the power supply and conduct 3-point correction (calibration).

## Conditions in use for CE conformity

 This product is CE compliant and complies with EMC directives. EN 61000-6-2 is the applicable standard that covers immunities relating to use of this product, but in order to comply with this standard, the following conditions must be satisfied.

### Conditions

- The controller should be connected less than 10 m 32.808 ft from the power supply.
- · The signal line to connect with the controller should be less than 30 m 98.425 ft.
- A ferrite clamp must be mounted within 10 mm 0.394 in from connector fitted onto the GP-XBCC3 cable with connector on one end for BCD output units.

#### Linearity in case of disc-shaped or cylindrical objects

· In case the sensing object is disc-shaped or cylindrical, the linearity varies with the sensing object size. In the event the sensing object is larger than the sizes indicated in the table below, the linearity specification (within ±0.3 % F.S.) is satisfied by performing zeroadjustment and span adjustment when in contact using the scaling function.

<In case of disc>

	Sensor head	Disc diameter ø (mm in)	Cylinder diameter ø (mm in)
	GP-X3SE	6 0.236	16 0.630
t: 1 mm +0 (mm)+	GP-X5SE	8 0.315	16 0.630
0.039 in	GP-X8S	12 0.472	50 1.969
n case of cylinder>	GP-X10M	12 0.472	50 1.969
	GP-X12ML	25 0.984	55 2.165
Iron cylinder	GP-X22KL	30 1.181	165 6.496

## **≀**: 135 mm

## Mounting sensor head

• The tightening torque should be under the value given below.

#### Mounting with set screw

Make sure to use an M3 or smaller set screw having a cup-point.

Set screw (M3 or less) 1 /1 (Cup-point)

- / - A	up-point)		
	Model No.	A (mm in)	Tightening torque
	GP-X3SE	4 to 16 0.157 to 0.630	0.10 N·m or less
	GP-X5SE	5 to 40 0 407 to 0 000	0.44 N·m or less
	GP-X8S	5 to 16 0.197 to 0.630	0.58 N·m or less

## Refer to p.1027 for general precautions.

Mounting with	nut		
<gp-x10m></gp-x10m>	<gp-x12ml></gp-x12ml>	GP-X22K	L>
Attached toothed lock washer -B- Mounting plate	Attached toot lock washer		ed toothed asher nting plate
Model No.	B (mm in)	Tightening torque	
GP-X10M	7 0.276 or more	9.8 N·m or less	_
GP-X12ML	14 0 551 or more	20 N·m or less	

GP-X22KL	20 0.787 or more (Note 1)	20 N·m or less	
Notes: 1) Without	nut. If a nut is installed,	the dimension will be 23.5 r	mm
0.926 in	or more.		

2) Mount such that the nuts do not protrude from the threaded portion.

#### Distance from surrounding metal

 As metal around the sensor head may affect the sensing performance, pay attention to the following points.

#### <Embedding of the sensor head in metal>

· Since the analog output may change if the sensor head is completely embedded in metal, keep the minimum distance specified in the table below.

Ť	
C [	
<b>↓</b> ►]	D Metal

	Sensor head	C (mm <mark>in</mark> )	D (mm in)
	GP-X3SE	ø10 ø0.394	
Metal	GP-X5SE	010 00.394	3 0.118
<i><!--///////////////////////////////////</i--></i>	GP-X8S	ø18 <mark>ø0.709</mark>	50.110
	GP-X10M	ø14 ø0.551	
	GP-X12ML	ø50 <mark>ø1.969</mark>	14 0.551
	GP-X22KL	ø50 <mark>ø1.969</mark>	20 0.787

#### Mutual interference

· If several sensor heads are mounted close together, some specifications may not be satisfied. Therefore, proceed with the interference prevention function enabled. The interference prevention function eliminates interference among sensors by alternating sensor oscillations. Contact our office for details about time charts etc.

If not using the interference prevention function, leave a distance more than the values given below.

<face face="" mounting="" to=""></face>	Sensor head	E (mm in)	F (mm in)
→ E ←	GP-X3SE	15 0.591	9 0.354
	GP-X5SE	30 1. <mark>18</mark> 1	11 0.433
<parallel mounting=""></parallel>	GP-X8S	40 1.575	15 0.591
↓	GP-X10M	40 1.575	15 0.591
F	GP-X12ML	170 <mark>6.693</mark>	50 1.969
	GP-X22KL	200 7.874	200 7.874

#### Sensing range

Ξ

 The sensing range is specified for the standard sensing object [stainless steel (SUS304) / iron [Cold rolled carbon steel (SPCC)], 60 × 60 × t 1 mm 2.362 × 2.362 × t 0.039 in]. For sensing metals other than the standard sensing objects, use the correction coefficient stated below as a guideline. Verify with the actual sensor before usina.

#### Correction coefficient

Sensor head	GP-X3SE GP-X10M GP-X5SE GP-X12ML GP-X8S GP-X22KL	
Stainless steel (SUS304), Iron	1	
Aluminum	0.5 approx.	

LASER SENSORS

PHOTO-ELECTRIC

SENSORS MICRO PHOTO-

PHOTO-ELECTRIC SENSORS

SAFETY COMPONENTS

PRESSURE SENSORS

INDUCTIVE PROXIMITY SENSORS

PARTICULAR

USE SENSORS

SENSOR OPTIONS

WIRE-SAVING

SYSTEMS

AREA SENSORS

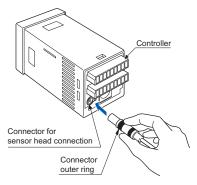
## PRECAUTIONS FOR PROPER USE

## Connection of sensor head and controller

• Make sure that the power supply is off while connecting the sensor head to the controller.

## Connection

• Hold the sensor head's connector by the outer ring and insert it into the connector provided on the controller for sensor head connection. Insert till you hear a click sound.

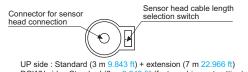


## Removing

• When removing, hold the connector outer ring and pull it straight out.

## Cable extension for sensor head

 When using a sensor head extension cable, turn the sensor head cable length selection switch side to the controller's sensor head connector to "3 m + 7 m 9.843 ft + 22.966 ft" with the power supply is off. After switching, reintroduce the power supply.

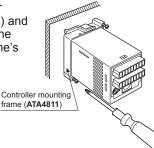


DOWN side : Standard (3 m 9.843 ft) (factory shipment setting)

 The coaxial connector for the extension cable is connected to the 0 V power supply. If installing to a metal plate or similar, insulate the connector from the surrounding metal.

## Mounting controller

 Use the attached controller mounting frame (ATA4811) and mount the controller onto the panel by fastening the frame's screws.



### Refer to p.1027 for general precautions.

- Refer to the "DIMENSIONS" (p.879) for the panel cut-out dimensions.
- The mountable panel thickness is 1 to 5 mm 0.039 to 0.197 in. However, if using a controller communication unit or BCD output unit, make the panel thickness between 1 and 2.5 mm 0.039 and 0.098 in.

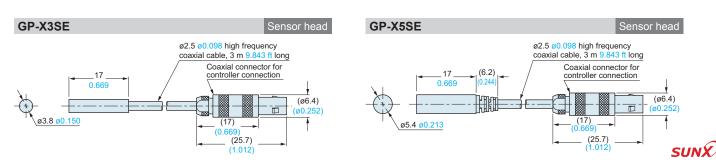
### Wiring

- Make sure that the power supply is off while wiring.
- Take care that wrong wiring will damage the sensor head or the controller.
- · Verify that the supply voltage variation is within the rating.
- If power is supplied from a commercial switching regulator, ensure that the frame ground (F.G.) terminal of the power supply is connected to an actual ground.
- In case noise generating equipment (switching regulator, inverter motor, etc.) is used in the vicinity of the sensor head or the controller, connect the frame ground (F.G.) terminal of the equipment to an actual ground.
- Do not run the wires together with high-voltage lines or power lines or put them in the same raceway. This can cause malfunction due to induction.
- Make sure to use an isolation transformer for the power supply. It an auto-transformer (single winding transformer) is used, this product or the power supply may get damaged.
- In case a surge is generated in the used power supply, connect a surge absorber to the supply and absorb the surge.
- The analog voltage output does not incorporate a shortcircuit protection circuit. Do not directly connect a power supply or a capacitive load.
- Make sure that stress by forcible bend or pulling is not applied directly to the sensor cable joint.
- If using separate power supplies for multiple controllers, use the same +V or 0 V supply for all.

## Others

- After turning on the power, wait 15 min. or more [20 min. for the **GP-XC3SE(-P)** and **GP-XC5SE(-P)**] before using the product. The power supply circuit is not stable immediately after the power is turned on, and this may cause measurement values to be distorted. In addition, note that there will also be a muting period of approx. 2 sec.
- This sensor is suitable for indoor use only.
- Avoid dust, dirt, and steam.
- Take care that the product does not come in direct contact with water, oil, grease, or organic solvents, such as, thinner, etc.

## DIMENSIONS (Unit: mm in) The CAD data in the dimensions can be downloaded from the SUNX website: http://www.sunx.com



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LASER MARKERS

STATIC CONTROL

Selection Guide Laser Displacement HL-C2 HL-C1 LM10 Magnetic Displacement GP-X GP-A Collinated Beam Sensors HL-T1 LA-300 LA

Other Produc



Selection Guide

Displacement

HL-C2

HL-C1

LM10

**GP-X** 

GP-A

Collimated Beam Sensors

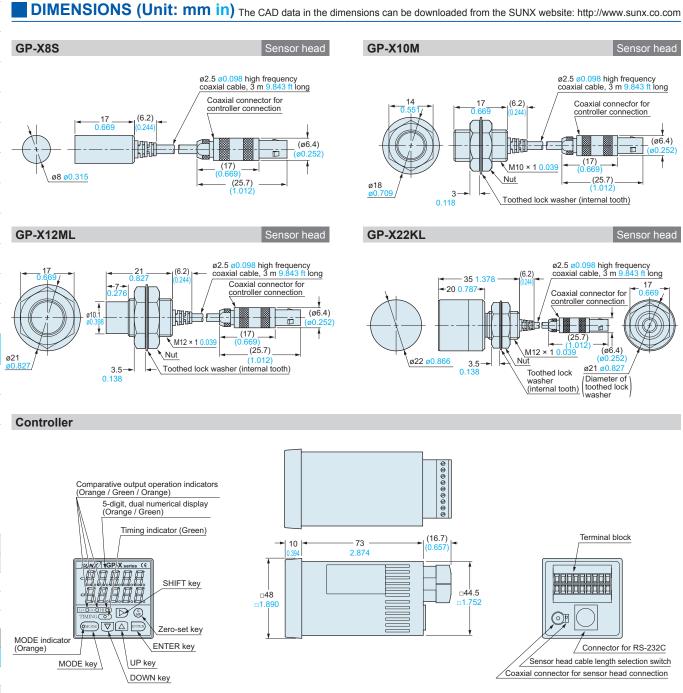
HL-T1

LA

Other Products

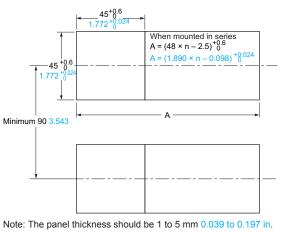
Laser

879



#### Panel cut-out dimensions

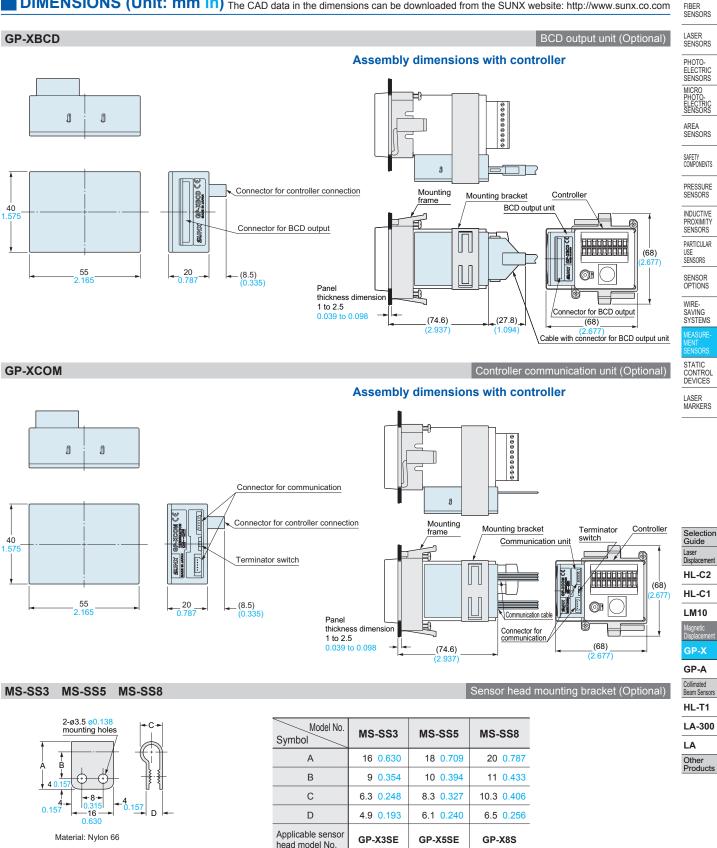
<When BCD output unit / controller communication unit not mounted>



Minimum 90 3.543

<When BCD output unit / controller communication unit mounted>

Note: The panel thickness should be 1 to 2.5 mm 0.039 to 0.098 in.



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